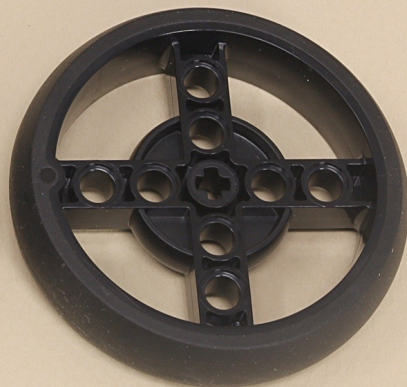
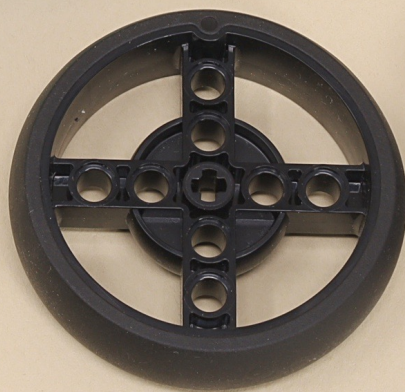
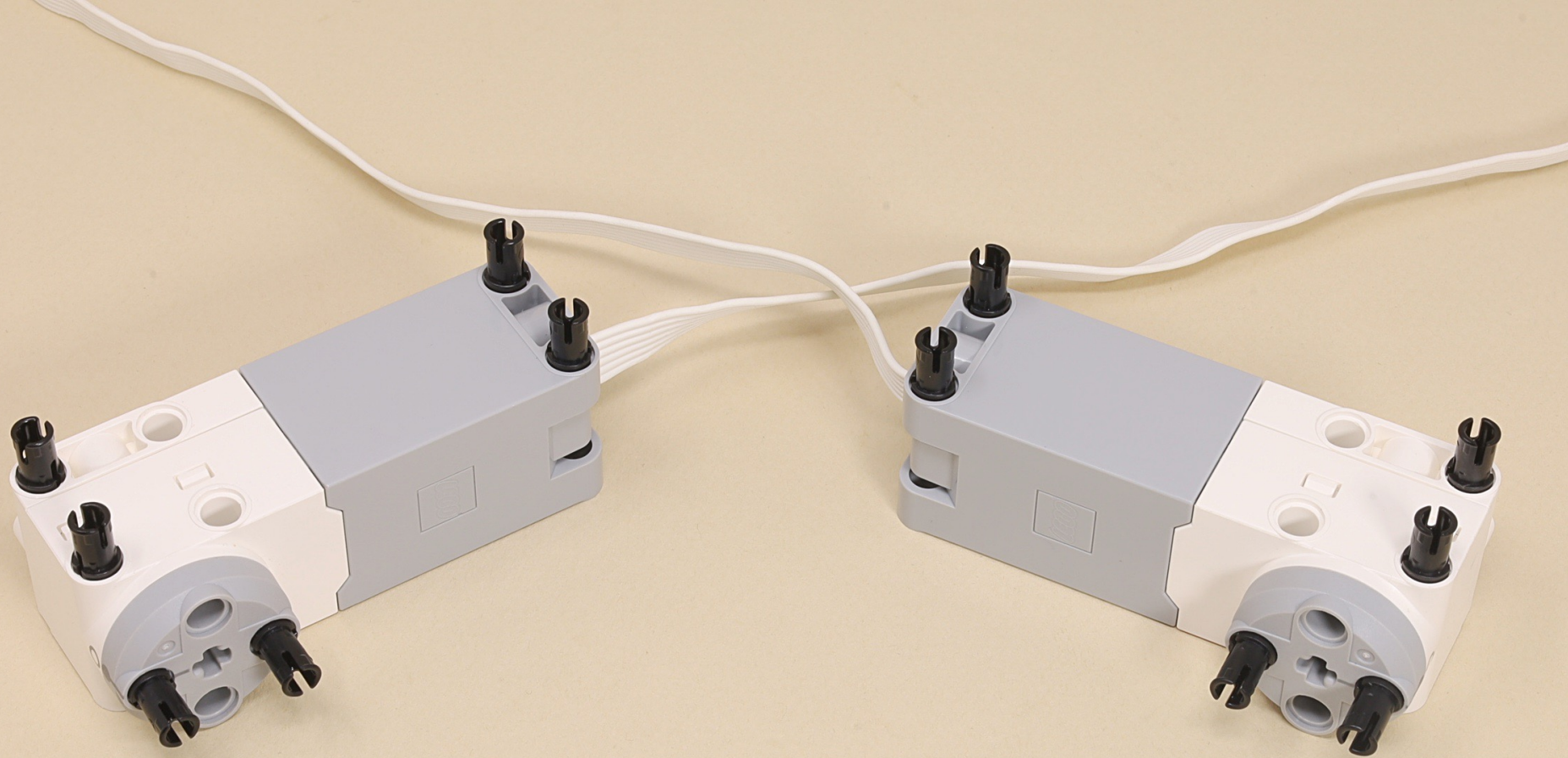
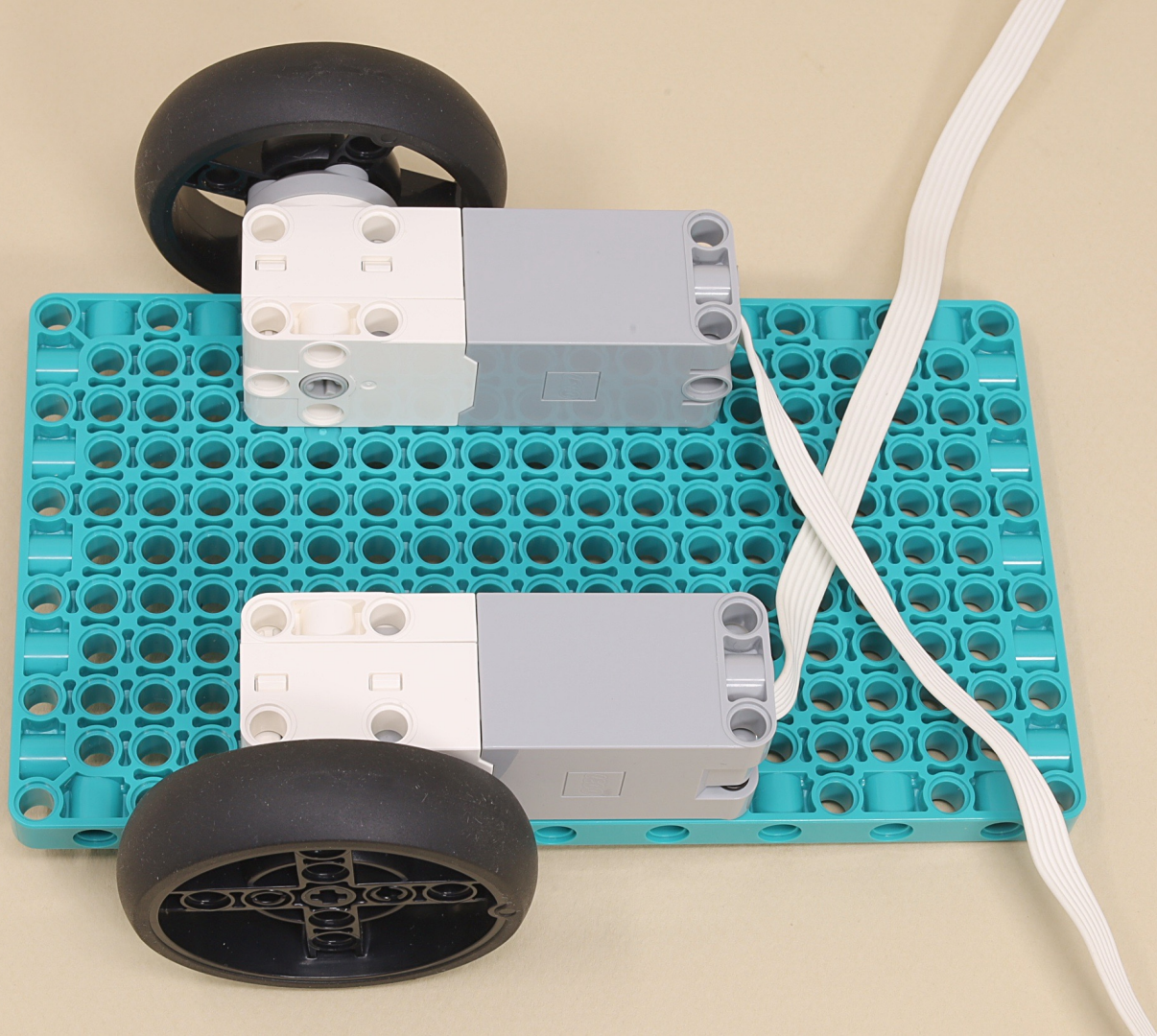
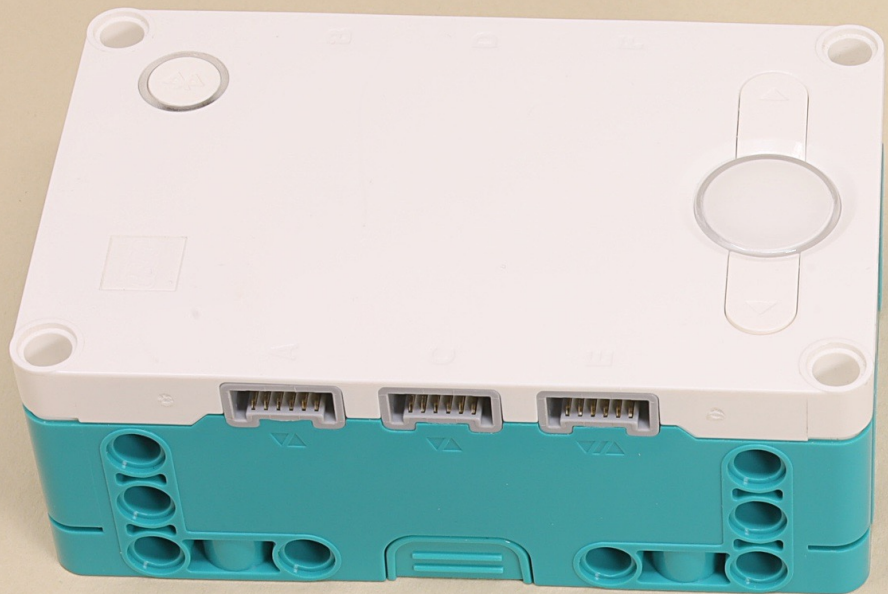


(12 x)

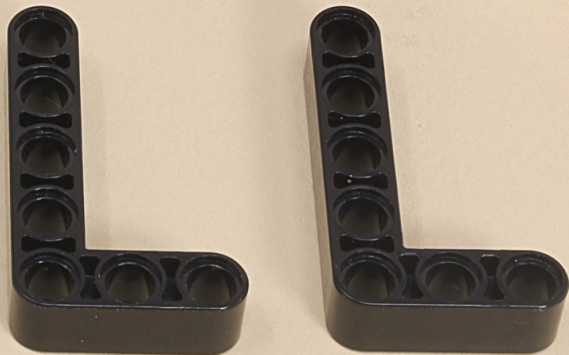




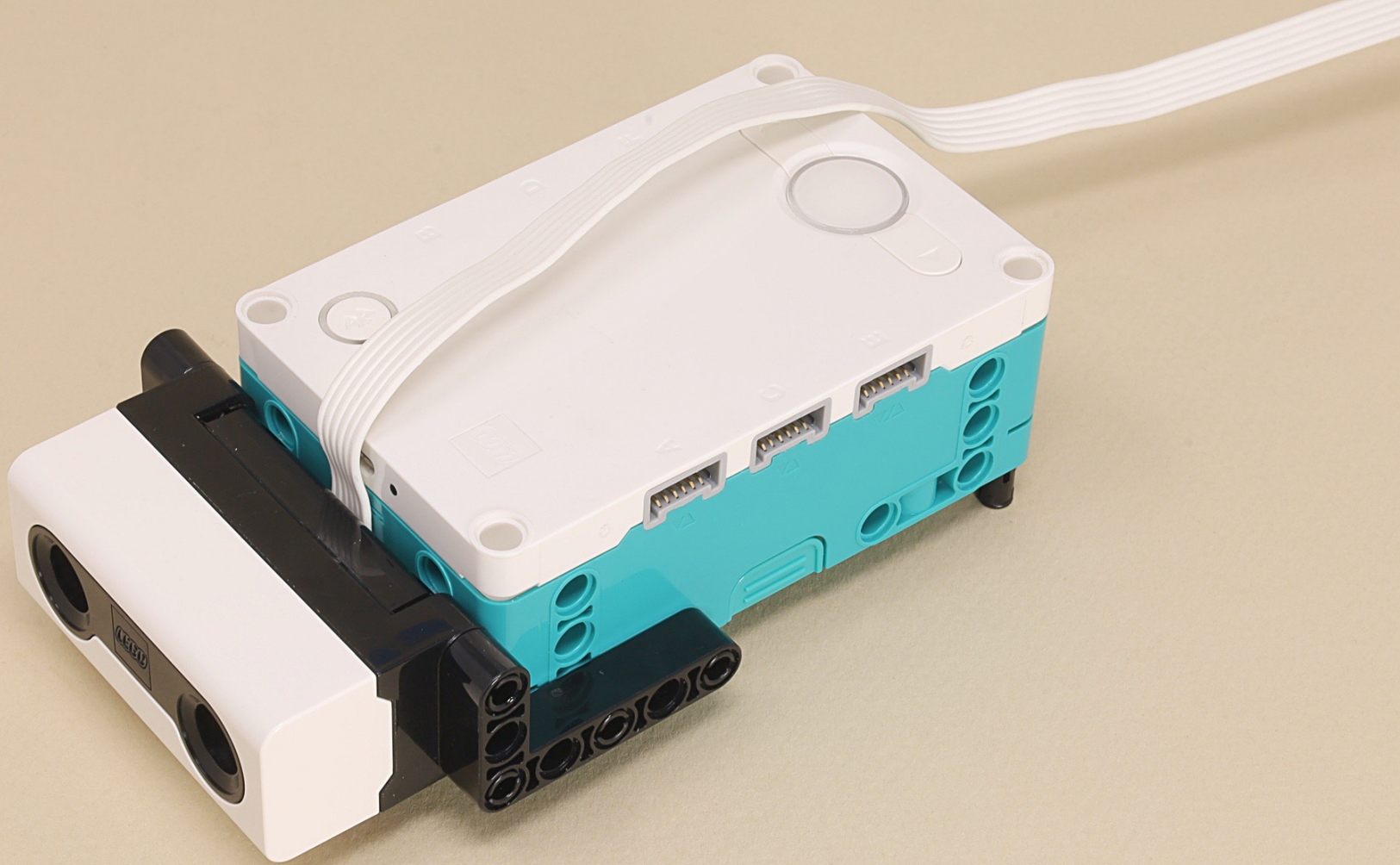


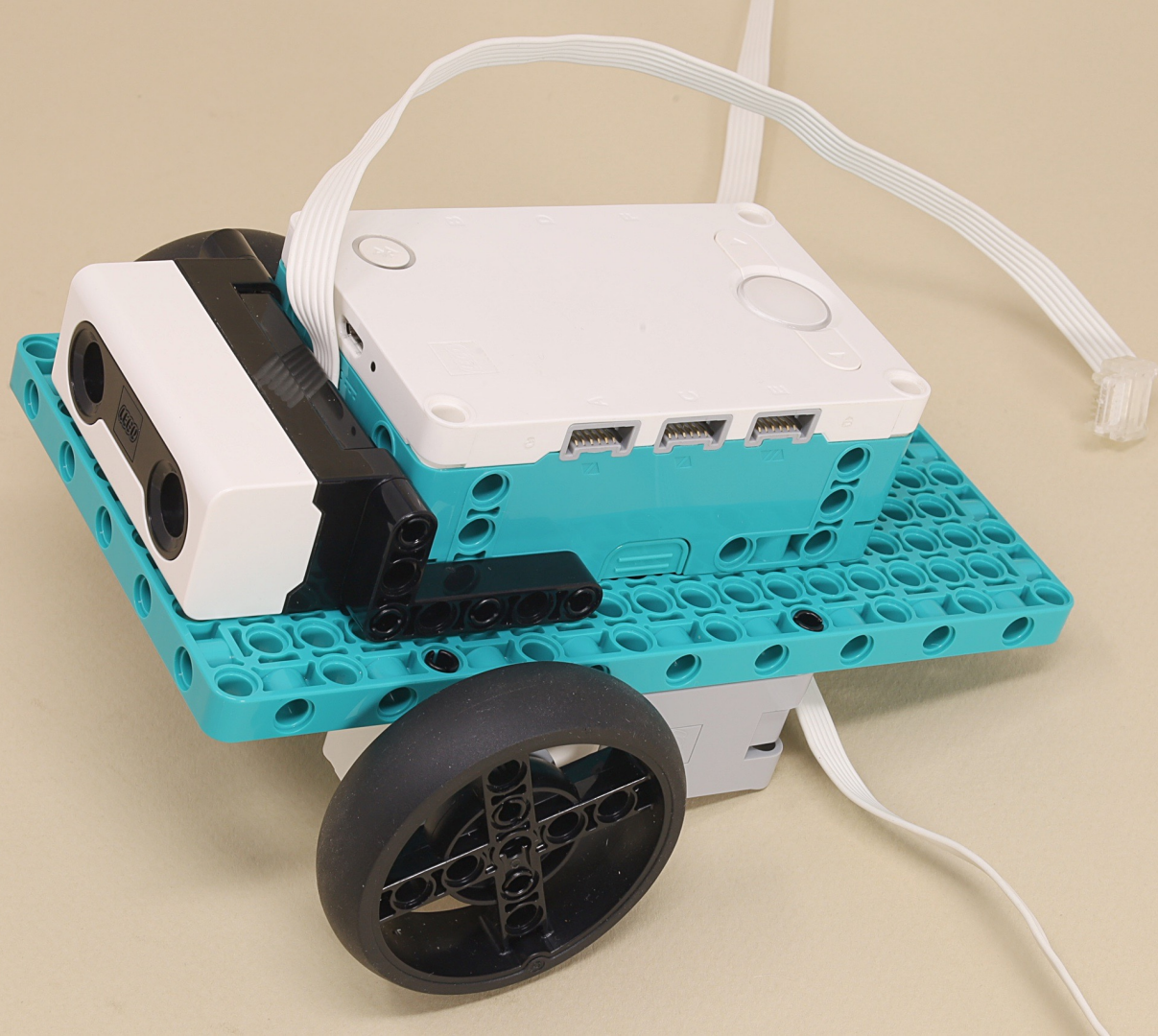


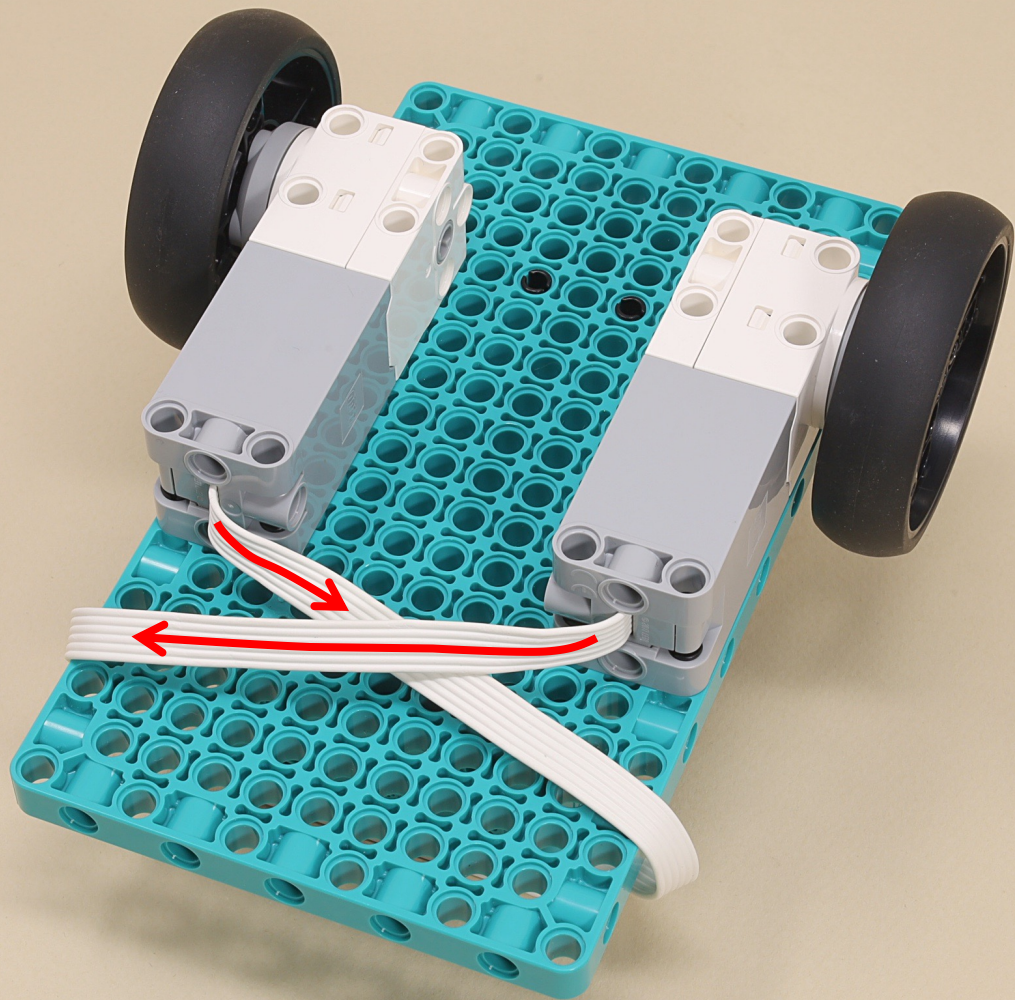
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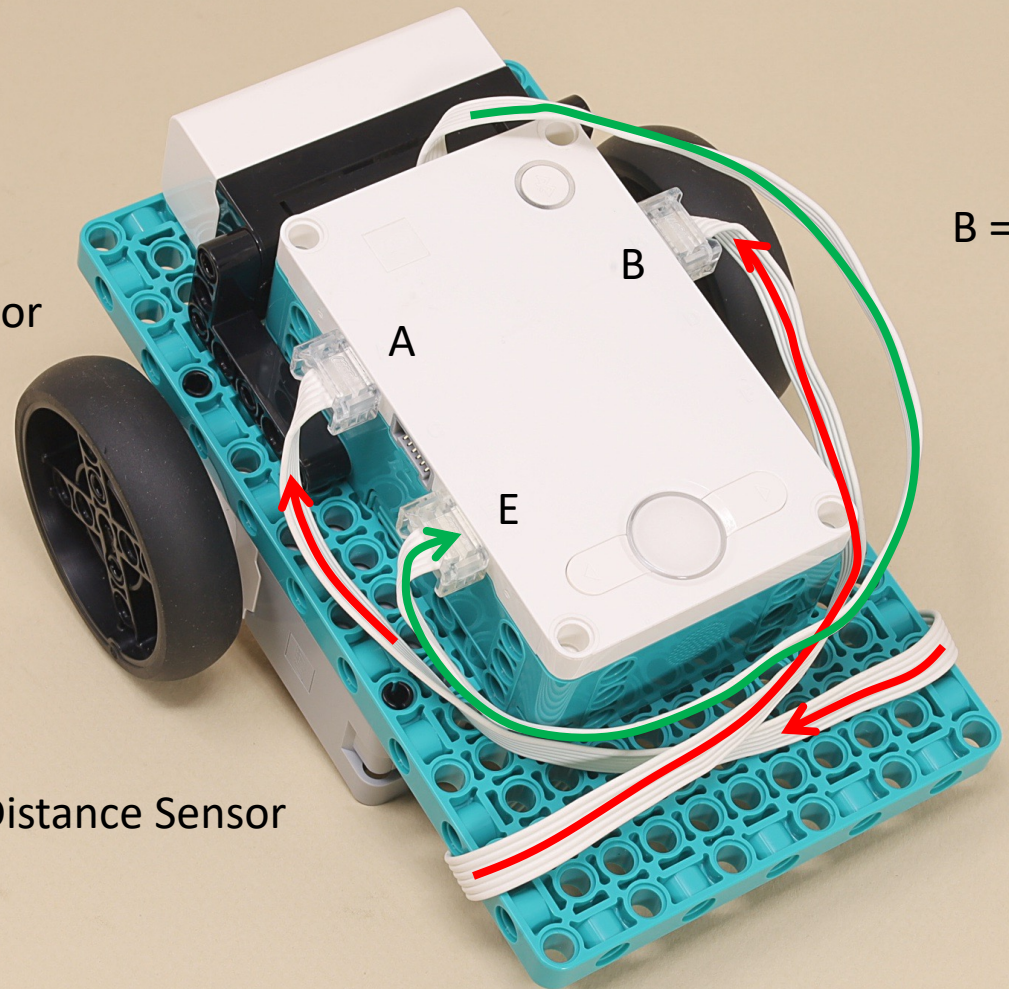


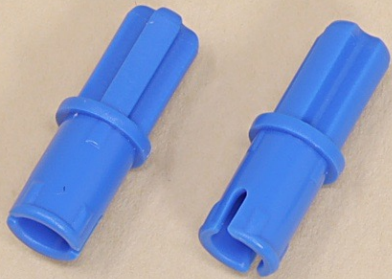


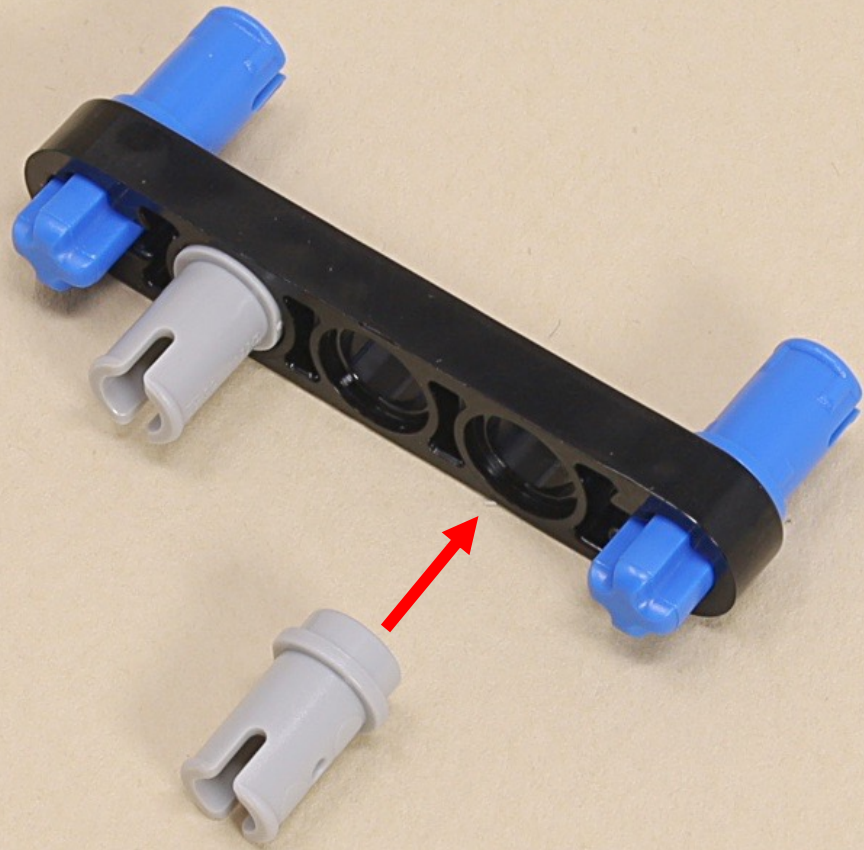
A = Left Drive Motor

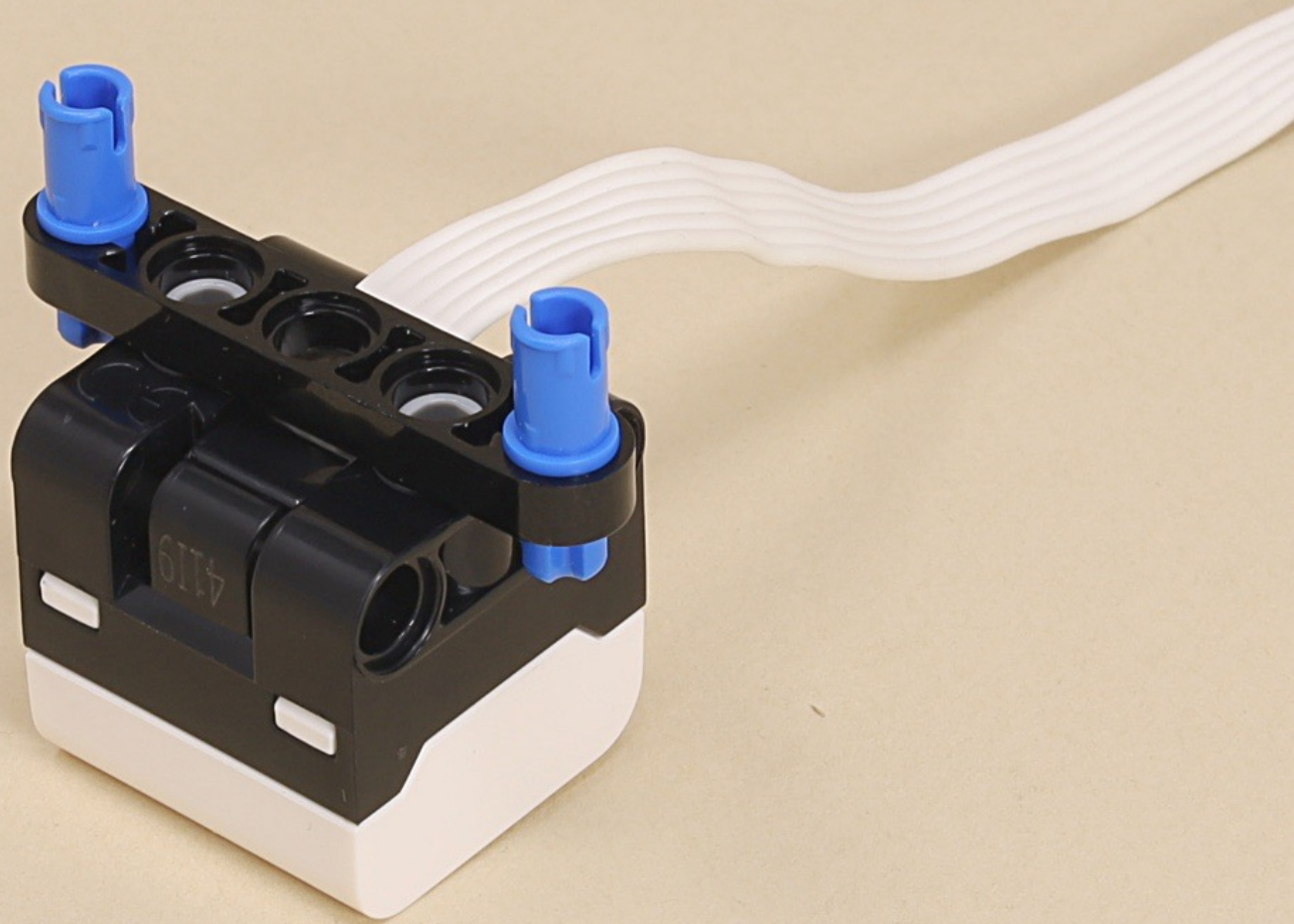
B = Right Drive Motor

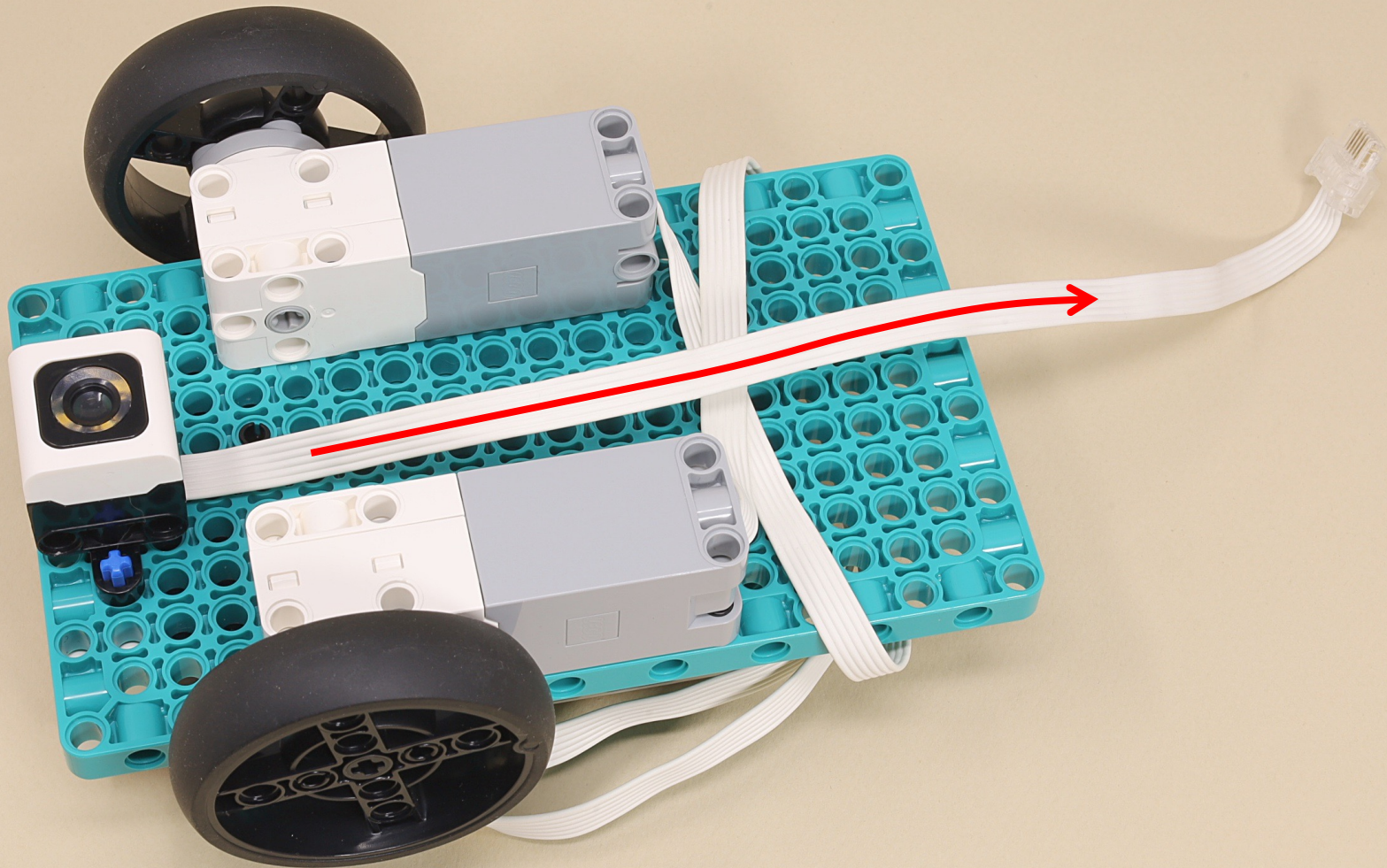
E = Distance Sensor

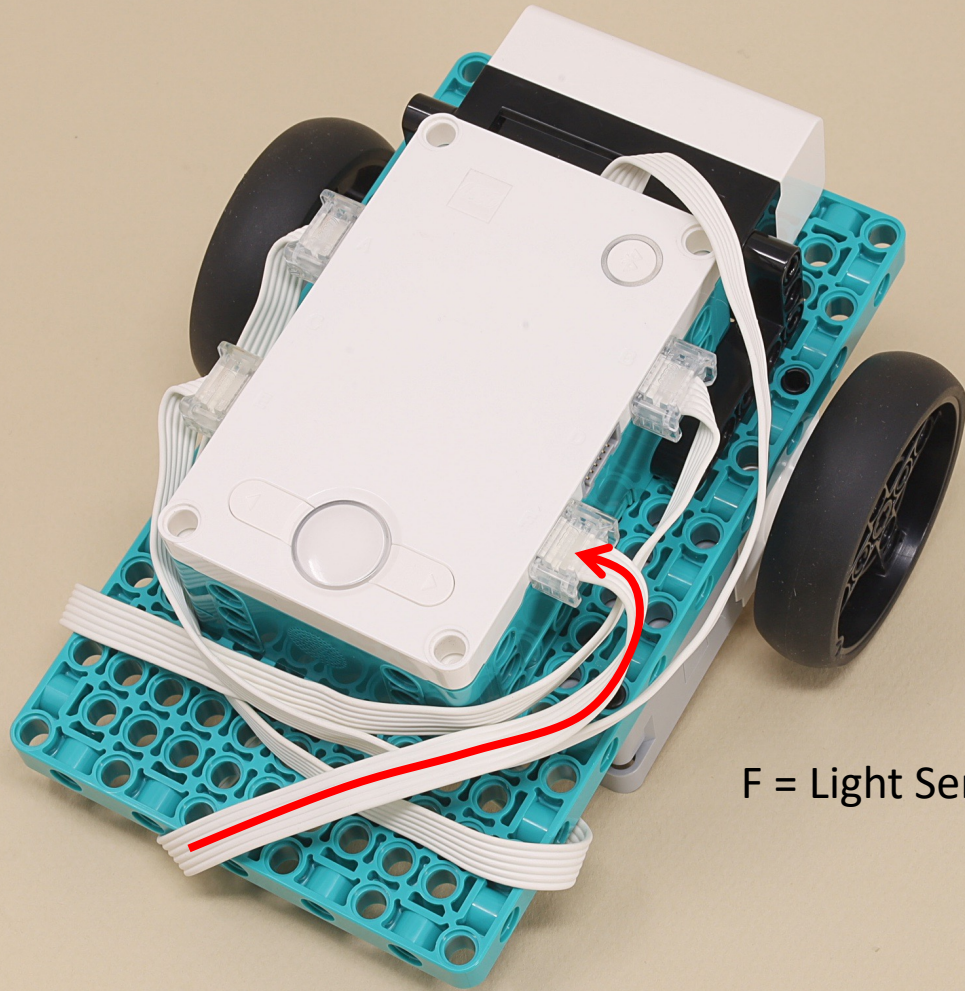












F = Light Sensor

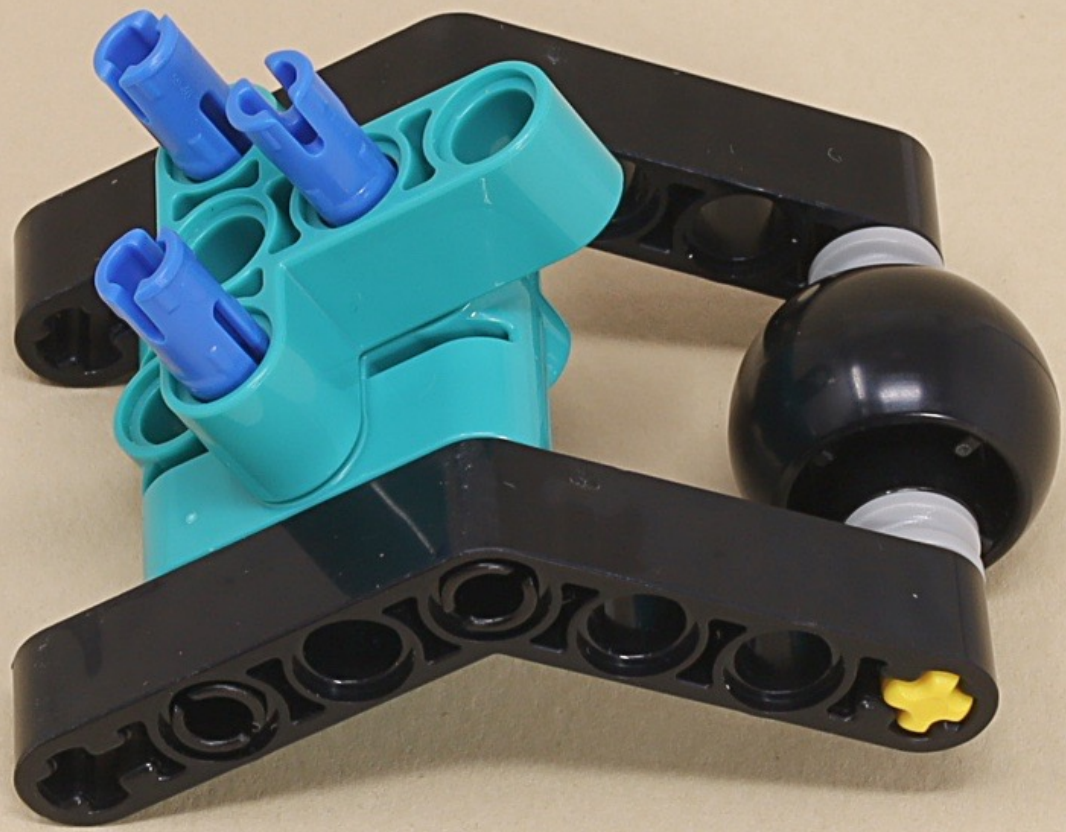


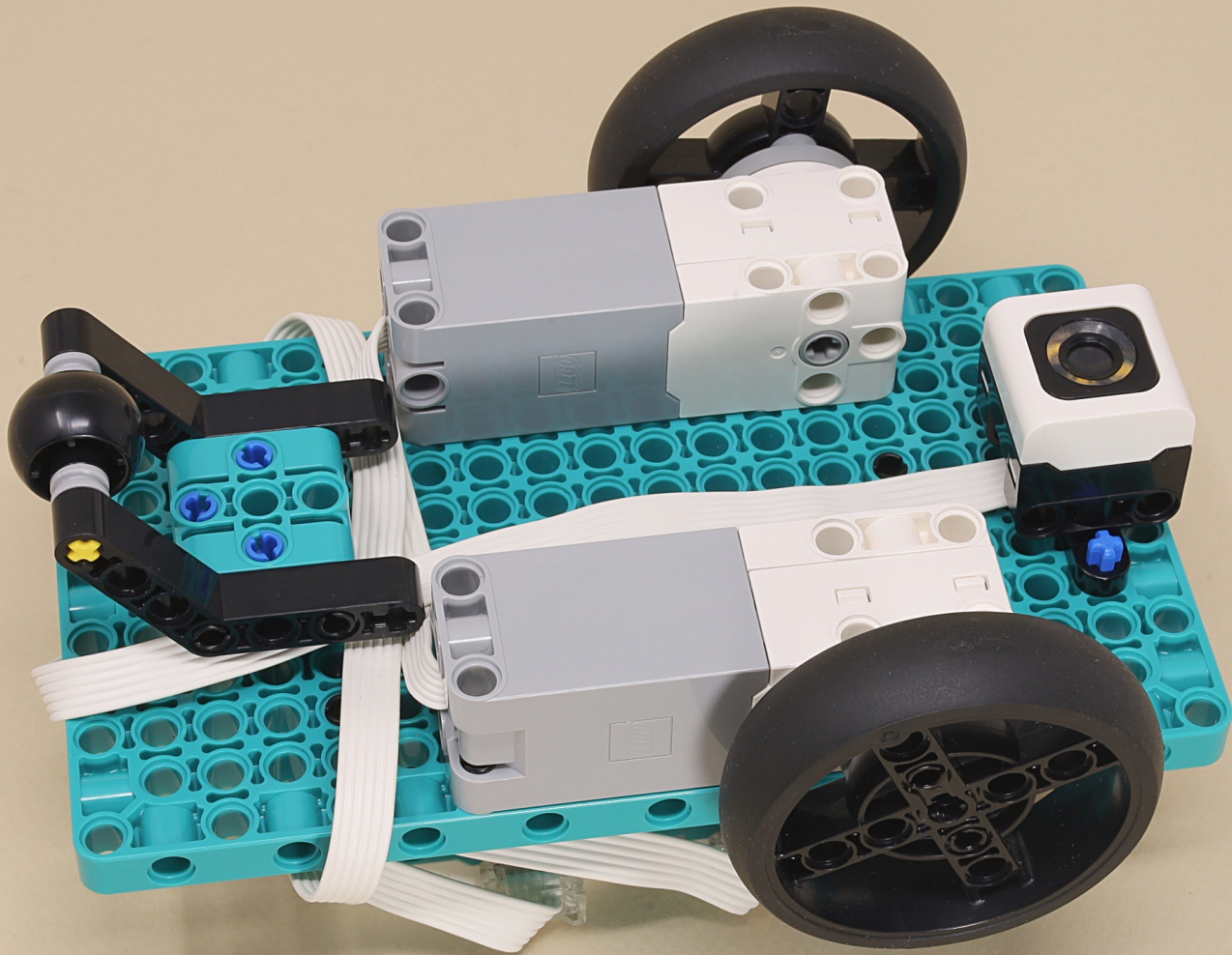
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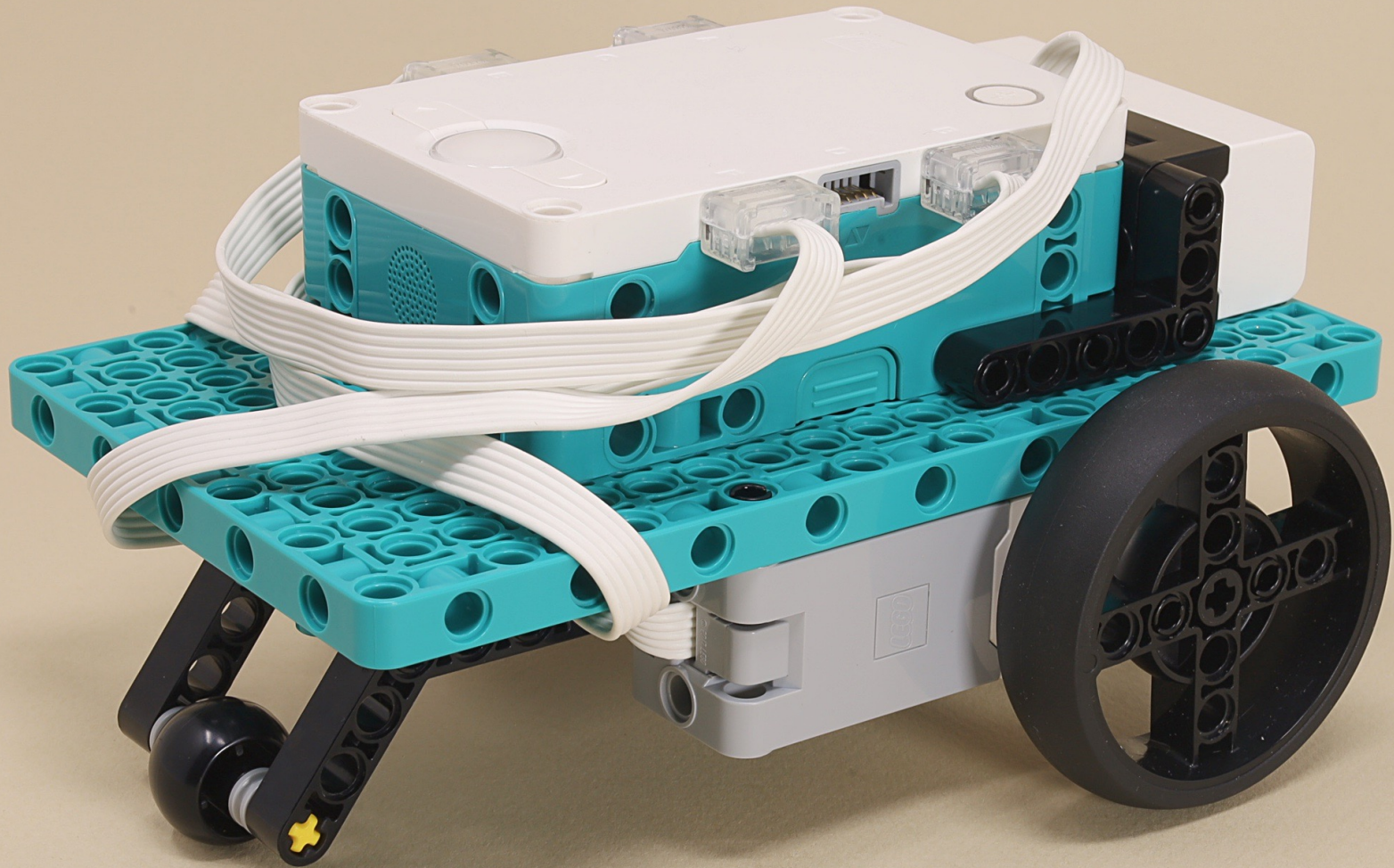










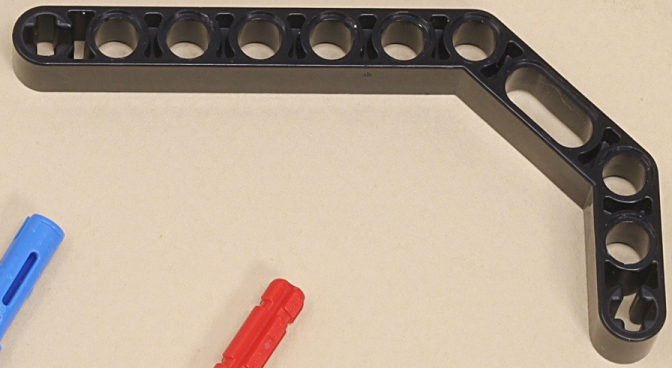


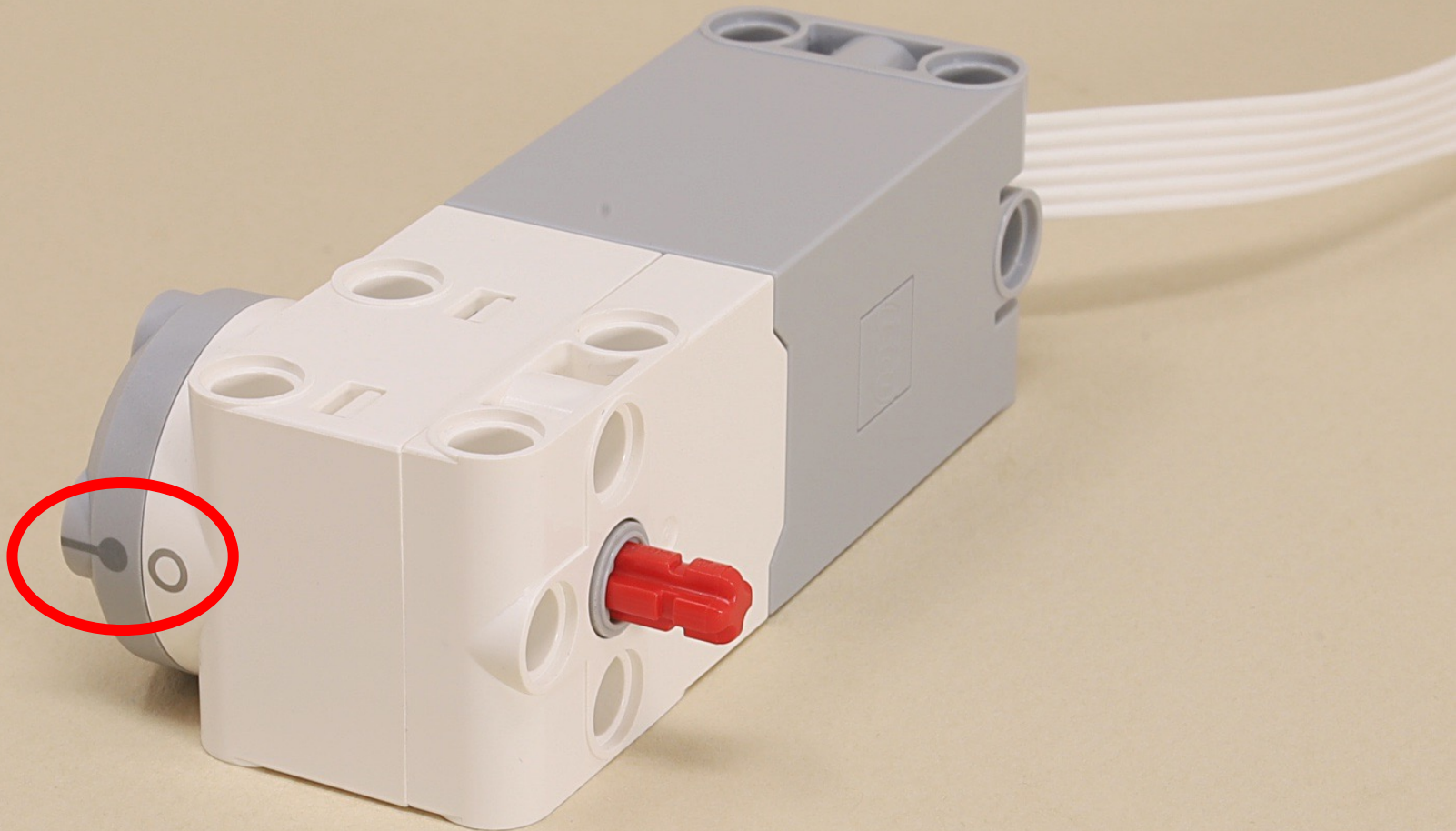


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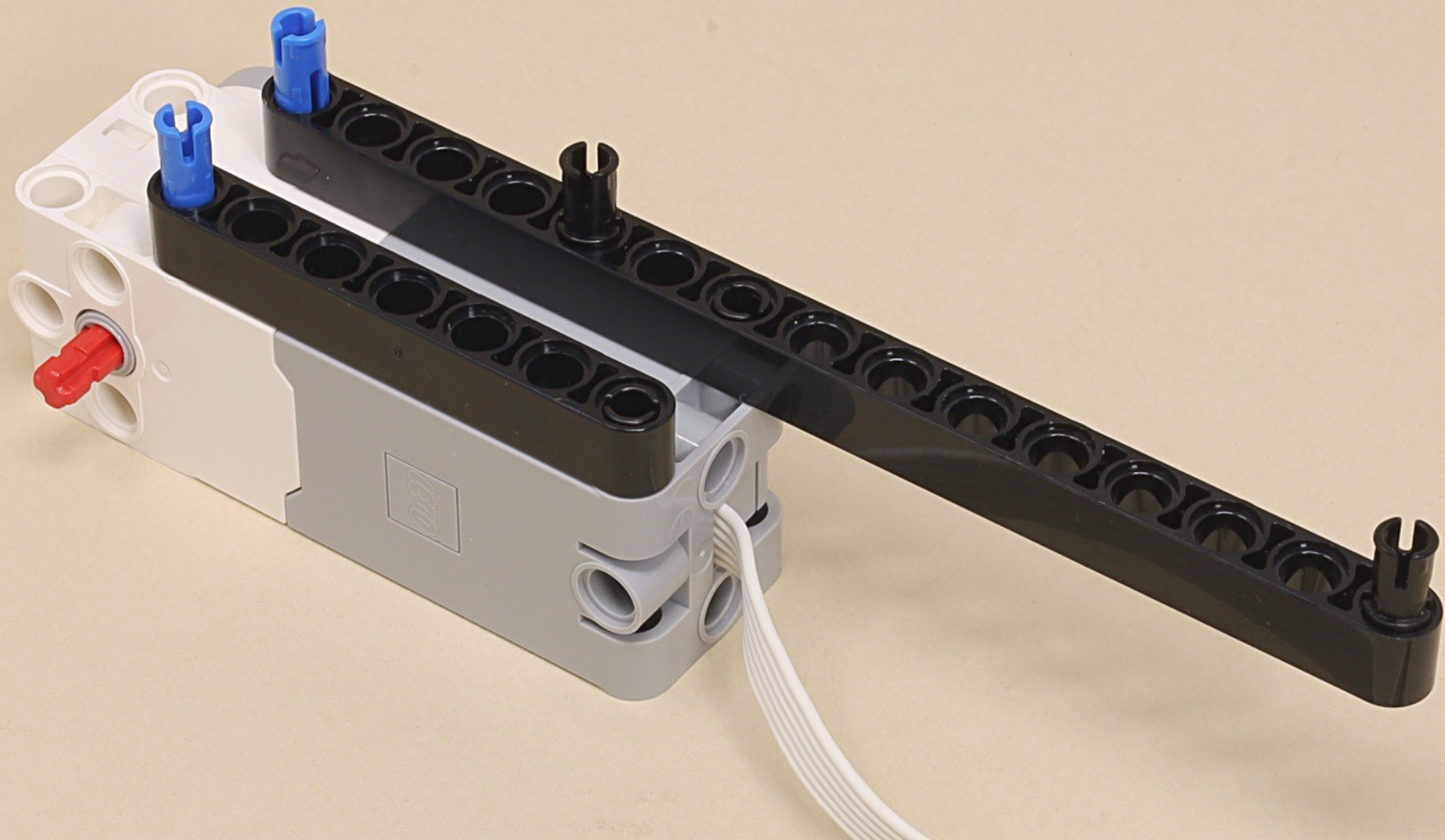


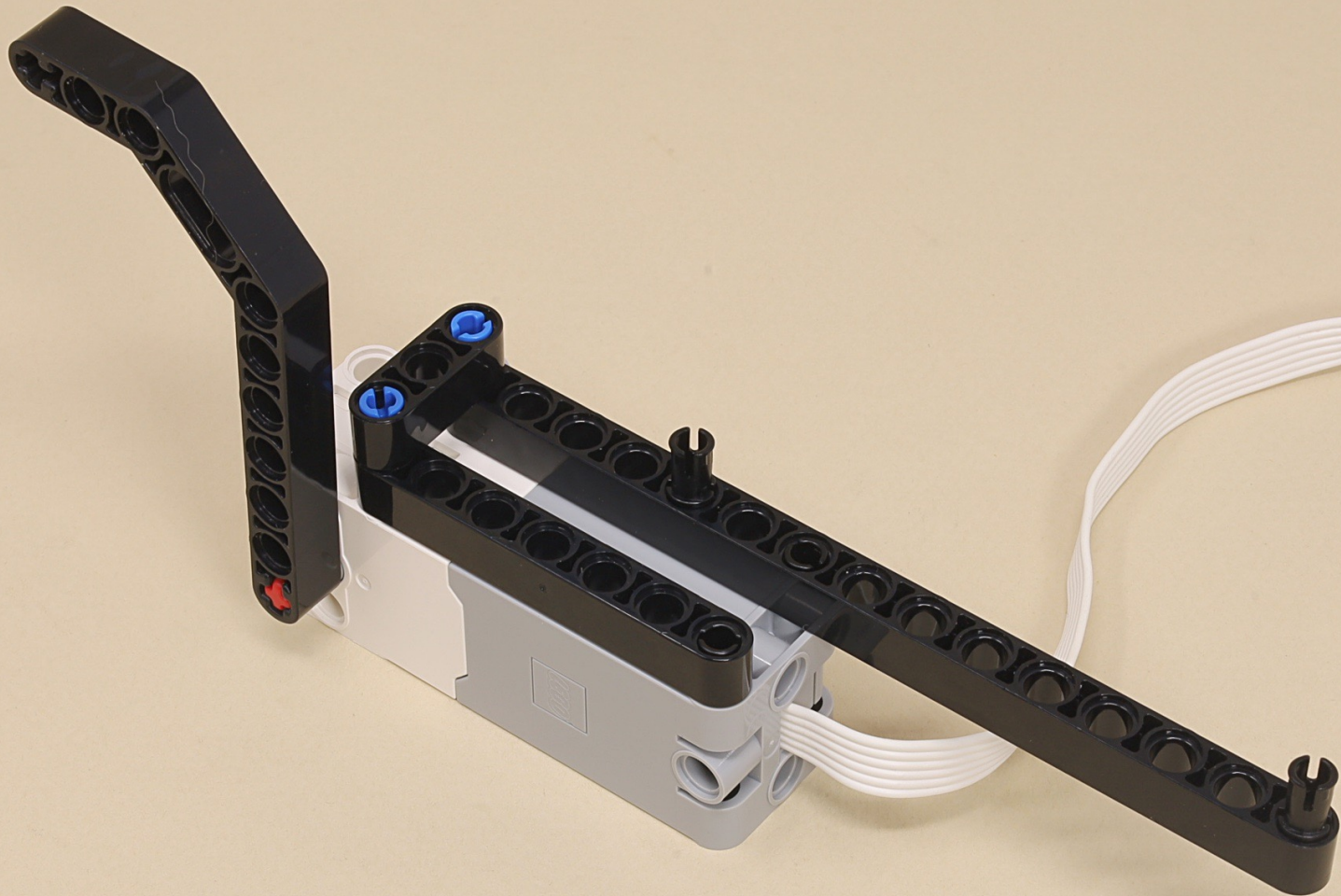
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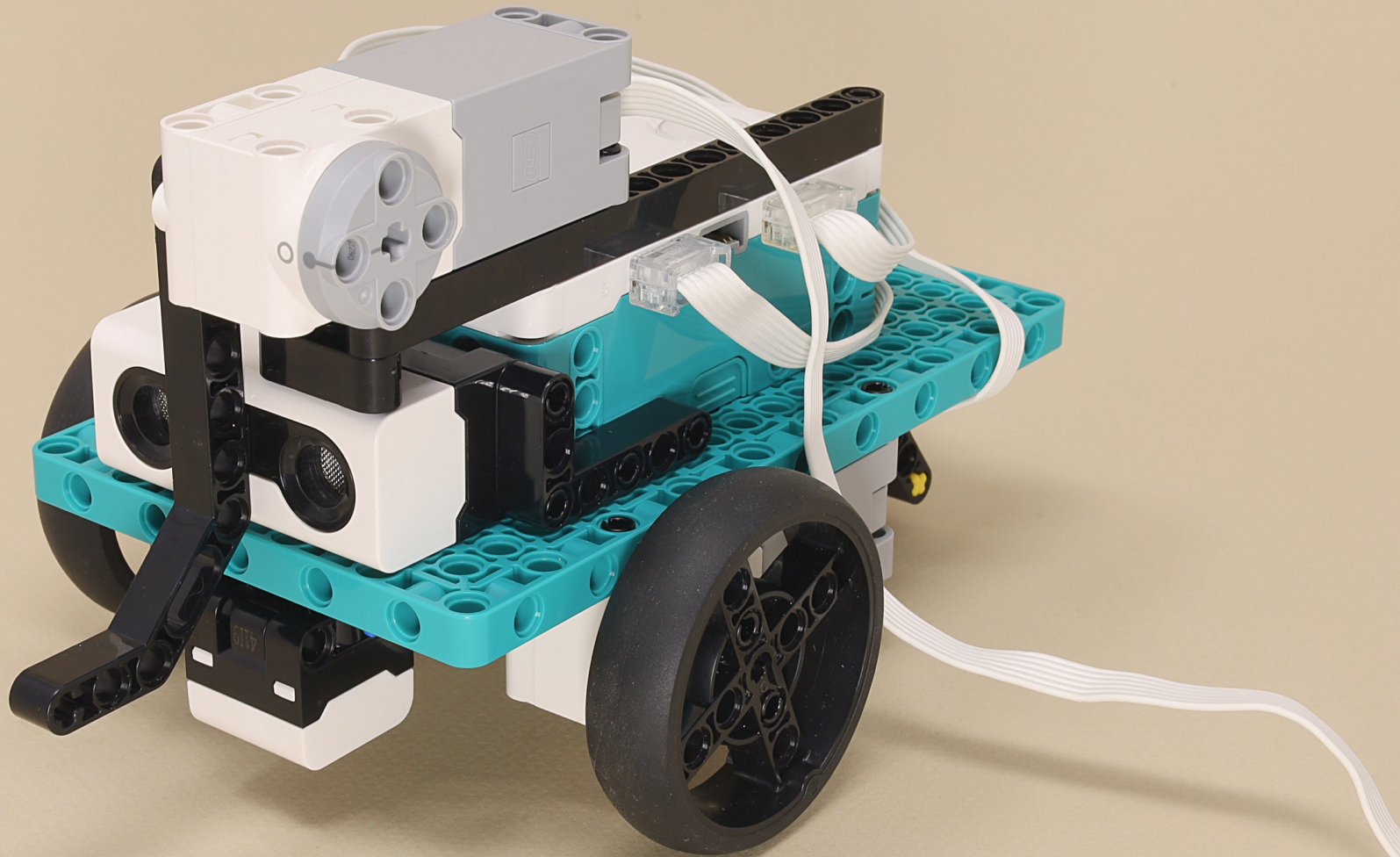


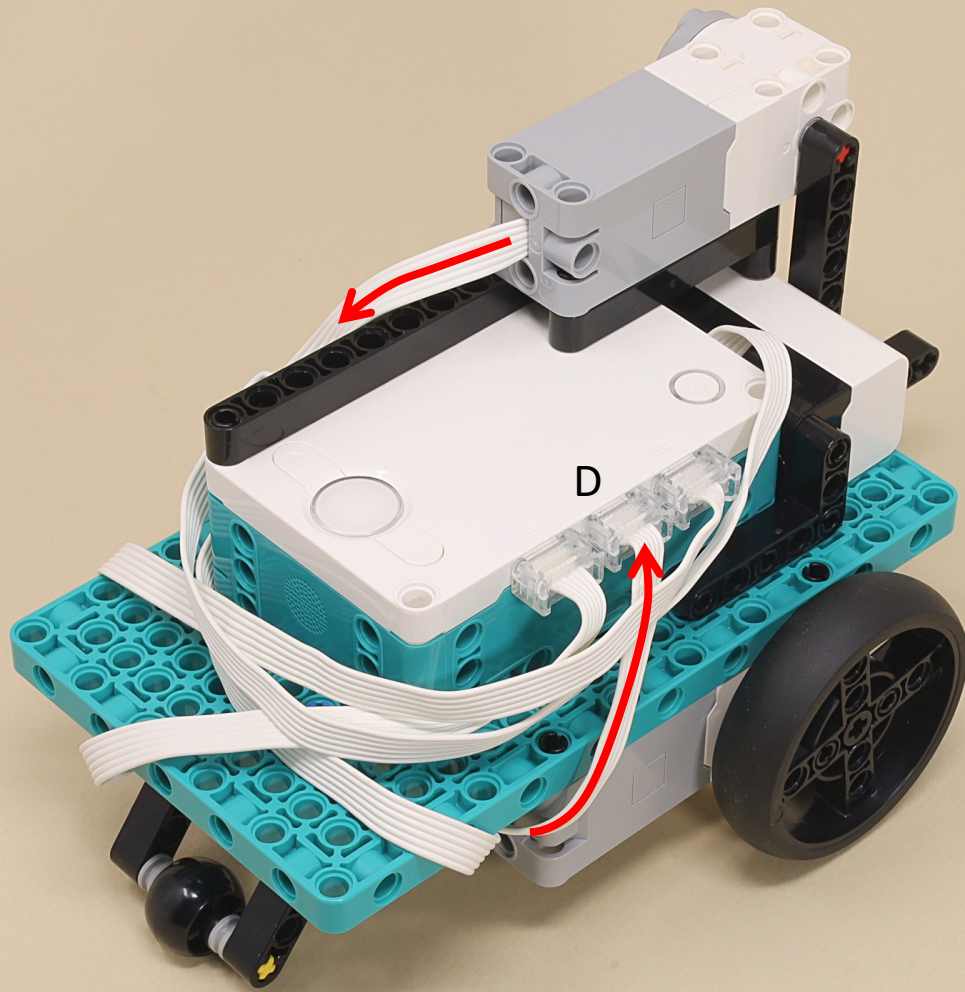






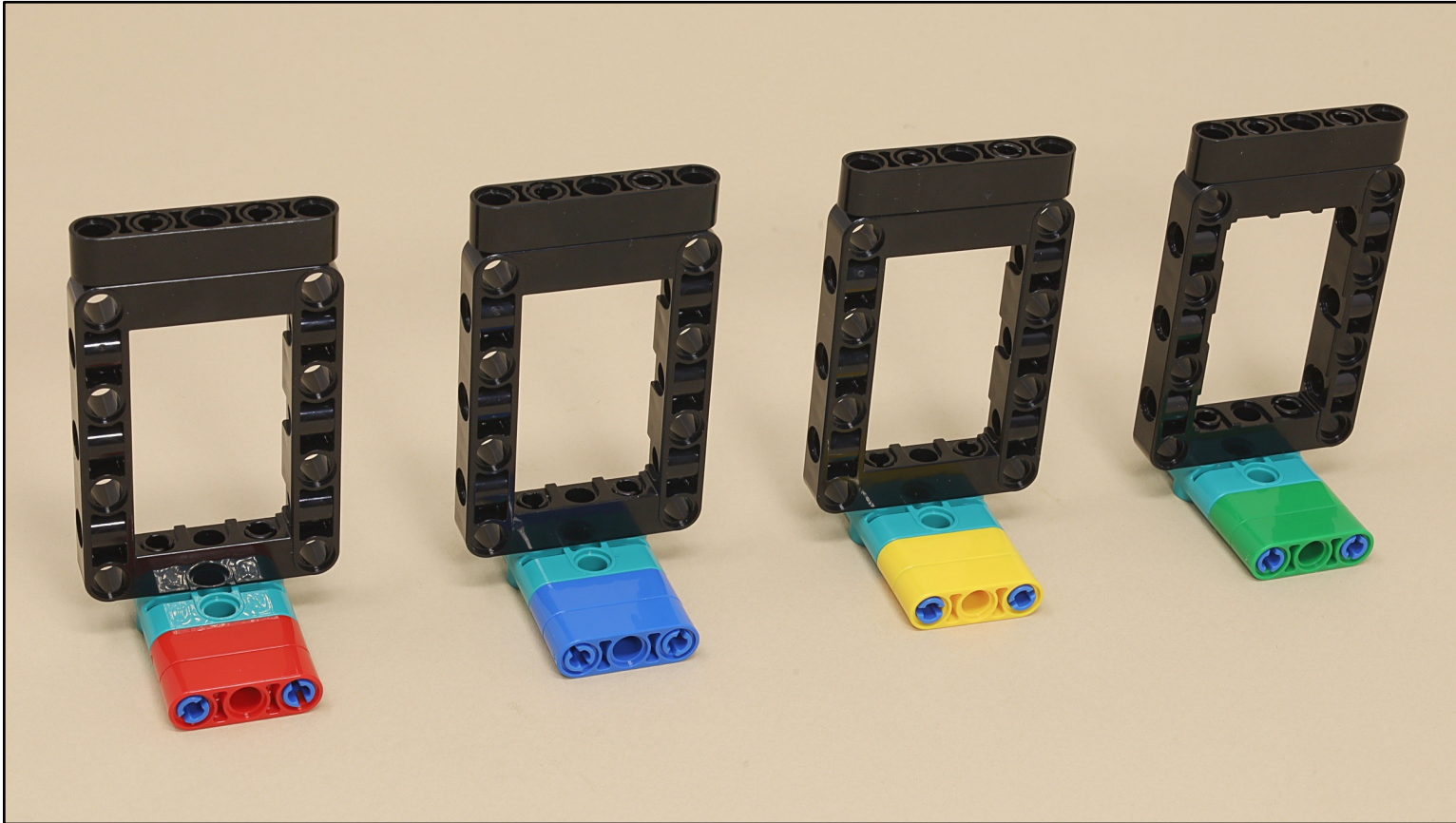






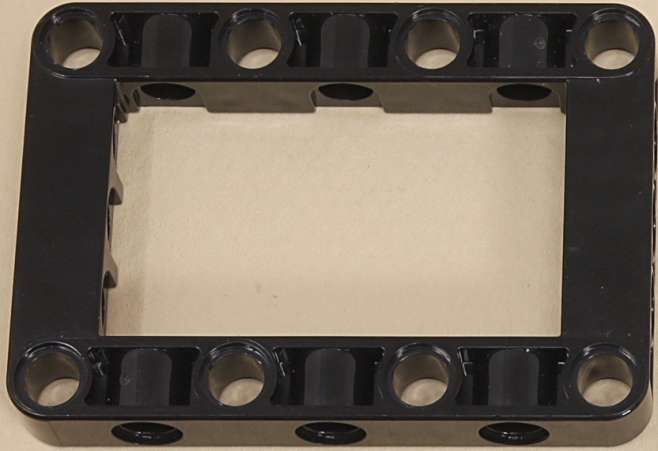
D = Arm Motor

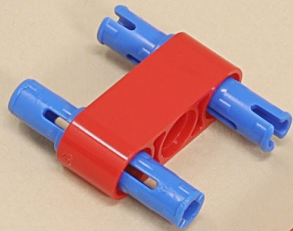
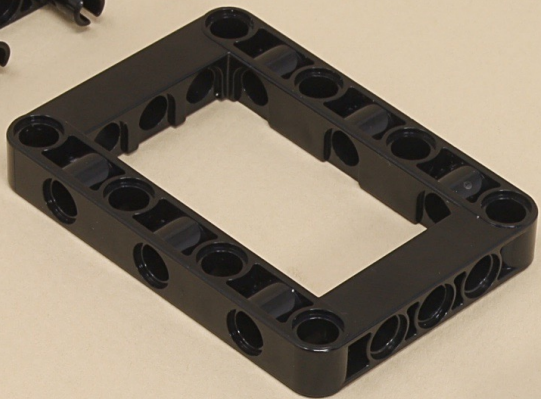
Loops for Practice Bot

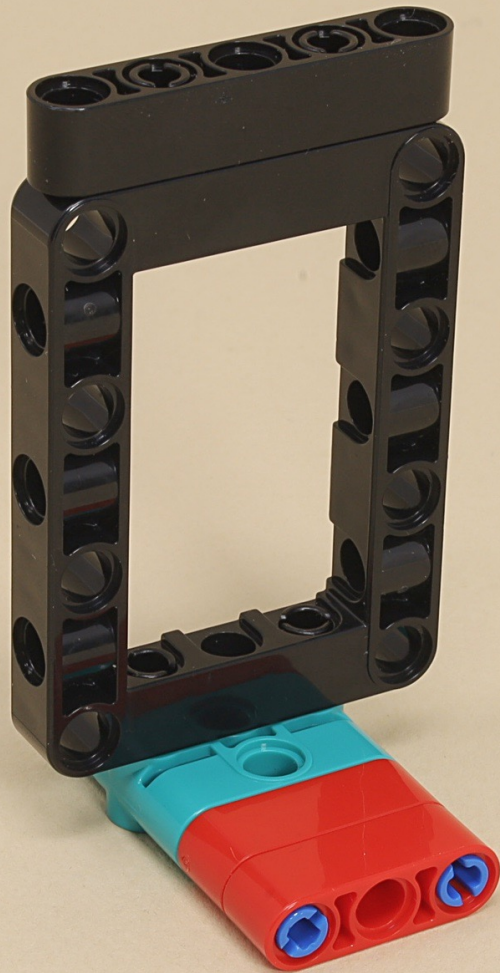


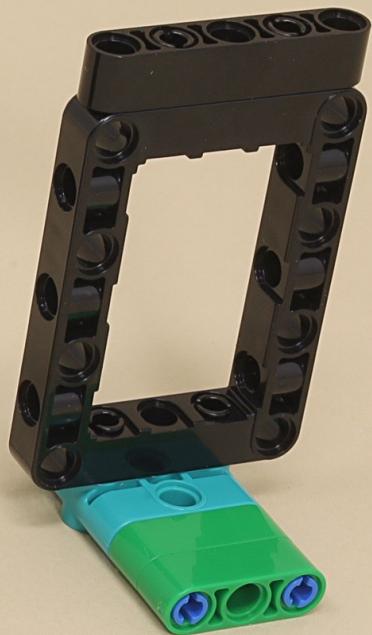
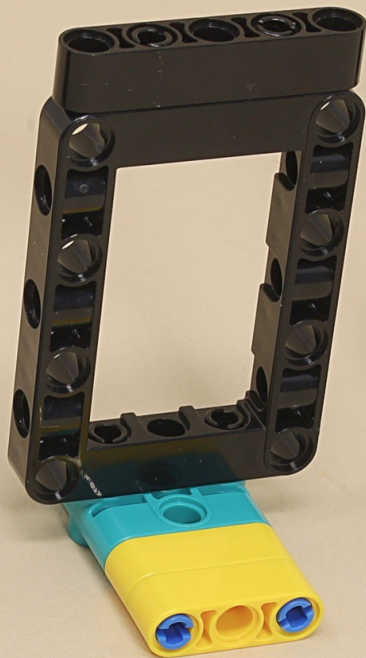
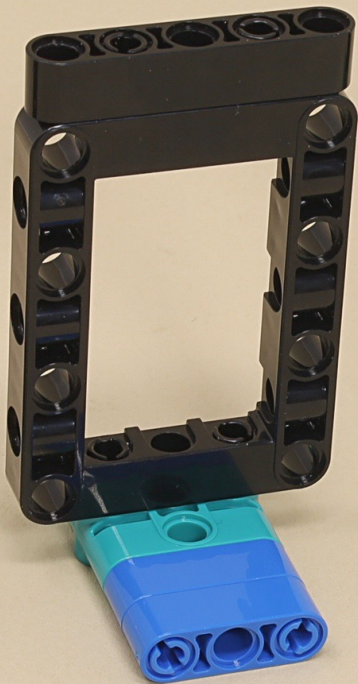
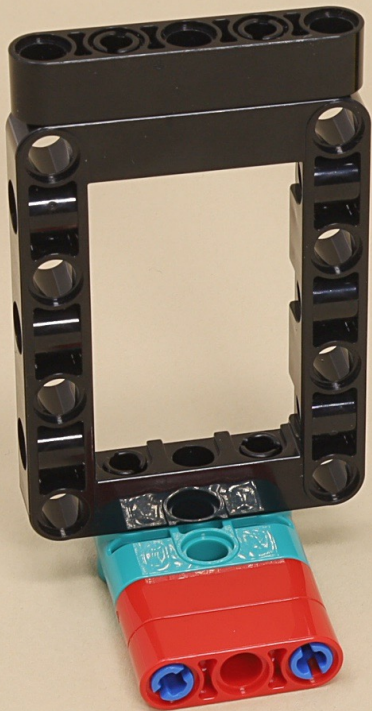
Scroll for
building
instructions

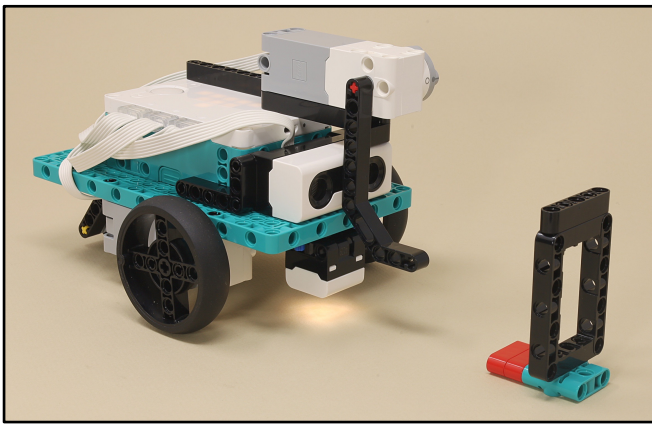




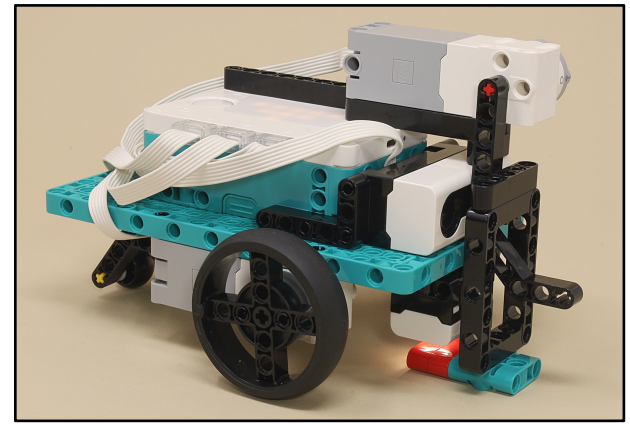




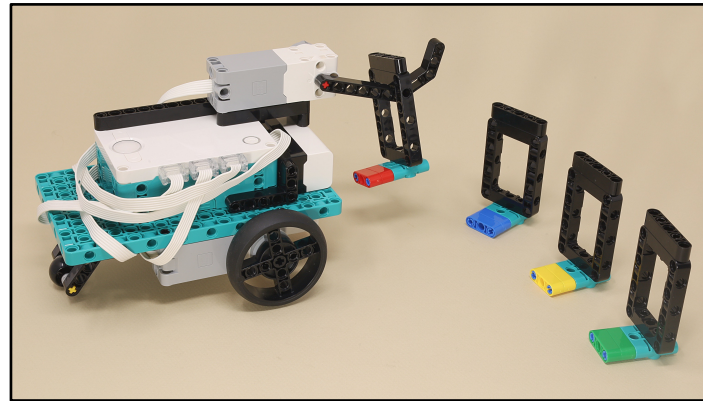




See loops with distance sensor



See loops with color sensor



Pick up loops, carry them, and place them back down